



SIMATIC S7-1500 COMPACT CPU CPU 1511C-1PN, CENTRAL PROCESSING UNIT WITH WORKING MEMORY 175 KB FOR PROGRAM AND 1 MB FOR DATA, 16 DIGITAL INPUTS, 16 DIGITAL OUTPUTS, 5 ANALOG INPUTS, 2 ANALOG OUTPUTS, 6 HIGH SPEED COUNTERS, 4 HIGH SPEED COUNTERS FOR PTO/PWM/FREQUENCY OUTPUT 1. INTERFACE: PROFINET IRT WITH 2 PORT SWITCH, 60 NS BIT-PERFORMANCE, INCL. FRONT CONNECTOR PUSH-IN, SIMATIC MEMORY CARD NECESSARY

General information	
Product type designation	CPU 1511C-1 PN
HW functional status	FS03
Firmware version	V2.0
Engineering with	
<ul style="list-style-type: none"> <li>STEP 7 TIA Portal configurable/integrated as of version</li> </ul>	V14
Configuration control	
via dataset	Yes
Display	
Screen diagonal (cm)	3.45 cm
Control elements	
Number of keys	6
Mode selector switch	1
Supply voltage	
Type of supply voltage	24 V DC
permissible range, lower limit (DC)	19.2 V; 20.4 V DC, for supplying the digital inputs/outputs

permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
<b>Mains buffering</b>	
• Mains/voltage failure stored energy time	5 ms; Refers to the power supply on the CPU section
<b>Input current</b>	
Current consumption (rated value)	0.8 A; Digital onboard I/O modules are supplied separately
Inrush current, max.	1.9 A; Rated value
$I^2t$	0.34 A <sup>2</sup> ·s
<b>Digital inputs</b>	
• from load voltage L+ (without load), max.	20 mA; per group
<b>Digital outputs</b>	
• from load voltage L+, max.	30 mA; Per group, without load
<b>Output voltage</b>	
Rated value (DC)	24 V
<b>Encoder supply</b>	
Number of outputs	1; One common 24 V encoder supply
<b>24 V encoder supply</b>	
• 24 V	Yes; L+ (-0.8 V)
• Short-circuit protection	Yes
• Output current, max.	1 A
<b>Power</b>	
Power consumption from the backplane bus (balanced)	8.5 W
Infeed power to the backplane bus	10 W
<b>Power loss</b>	
Power loss, typ.	11.8 W
<b>Memory</b>	
SIMATIC memory card required	Yes
<b>Work memory</b>	
• integrated (for program)	175 kbyte
• integrated (for data)	1 Mbyte
<b>Load memory</b>	
• Plug-in (SIMATIC Memory Card), max.	32 Gbyte
<b>Backup</b>	
• maintenance-free	Yes
<b>CPU processing times</b>	
for bit operations, typ.	60 ns
for word operations, typ.	72 ns
for fixed point arithmetic, typ.	96 ns
for floating point arithmetic, typ.	384 ns

## CPU-blocks

Number of elements (total)	2 000; Blocks (OB, FB, FC, DB) and UDTs
<b>DB</b>	
• Number range	1 ... 60 999; subdivided into: number range that can be used by the user: 1 ... 59 999, and number range of DBs created via SFC 86: 60 000 ... 60 999
• Size, max.	1 Mbyte; For non-optimized block accesses, the max. size of the DB is 64 KB
<b>FB</b>	
• Number range	0 ... 65 535
• Size, max.	175 kbyte
<b>FC</b>	
• Number range	0 ... 65 535
• Size, max.	175 kbyte
<b>OB</b>	
• Size, max.	175 kbyte
• Number of free cycle OBs	100
• Number of time alarm OBs	20
• Number of delay alarm OBs	20
• Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 500 µs
• Number of process alarm OBs	50
• Number of DPV1 alarm OBs	3
• Number of isochronous mode OBs	1
• Number of technology synchronous alarm OBs	2
• Number of startup OBs	100
• Number of asynchronous error OBs	4
• Number of synchronous error OBs	2
• Number of diagnostic alarm OBs	1
<b>Nesting depth</b>	
• per priority class	24

## Counters, timers and their retentivity

<b>S7 counter</b>	
• Number	2 048
<b>Retentivity</b>	
— adjustable	Yes
<b>IEC counter</b>	
• Number	Any (only limited by the main memory)
<b>Retentivity</b>	
— adjustable	Yes
<b>S7 times</b>	
• Number	2 048
<b>Retentivity</b>	

— adjustable	Yes
<b>IEC timer</b>	
• Number	Any (only limited by the main memory)
<b>Retentivity</b>	
— adjustable	Yes
<b>Data areas and their retentivity</b>	
<b>Flag</b>	
• Number, max.	16 kbyte
• Number of clock memories	8; 8 clock memory bits, grouped into one clock memory byte
<b>Data blocks</b>	
• Retentivity adjustable	Yes
• Retentivity preset	No
<b>Local data</b>	
• per priority class, max.	64 kbyte; max. 16 KB per block
<b>Address area</b>	
Number of IO modules	1 024; max. number of modules / submodules
<b>I/O address area</b>	
• Inputs	32 kbyte; All inputs are in the process image
• Outputs	32 kbyte; All outputs are in the process image
<b>per integrated IO subsystem</b>	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
<b>per CM/CP</b>	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
<b>Subprocess images</b>	
• Number of subprocess images, max.	32
<b>Hardware configuration</b>	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
<b>Number of DP masters</b>	
• Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
<b>Number of IO Controllers</b>	
• integrated	1
• Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
<b>Rack</b>	
• Modules per rack, max.	32; CPU + 31 modules
• Number of lines, max.	1

<b>PtP CM</b>	
<ul style="list-style-type: none"> <li>Number of PtP CMs</li> </ul>	the number of connectable PtP CMs is only limited by the number of available slots
<b>Time of day</b>	
<b>Clock</b>	
<ul style="list-style-type: none"> <li>Type</li> <li>Backup time</li> <li>Deviation per day, max.</li> </ul>	<p>Hardware clock</p> <p>6 wk; At 40 °C ambient temperature, typically</p> <p>10 s; Typ.: 2 s</p>
<b>Operating hours counter</b>	
<ul style="list-style-type: none"> <li>Number</li> </ul>	16
<b>Clock synchronization</b>	
<ul style="list-style-type: none"> <li>supported</li> <li>in AS, master</li> <li>in AS, slave</li> <li>on Ethernet via NTP</li> </ul>	<p>Yes</p> <p>Yes</p> <p>Yes</p> <p>Yes</p>
<b>Digital inputs</b>	
integrated channels (DI)	16
Digital inputs, parameterizable	Yes
Source/sink input	P-reading
Input characteristic curve in accordance with IEC 61131, type 3	Yes
<b>Digital input functions, parameterizable</b>	
<ul style="list-style-type: none"> <li>Gate start/stop</li> <li>Capture</li> <li>Synchronization</li> </ul>	<p>Yes</p> <p>Yes</p> <p>Yes</p>
<b>Input voltage</b>	
<ul style="list-style-type: none"> <li>Type of input voltage</li> <li>Rated value (DC)</li> <li>for signal "0"</li> <li>for signal "1"</li> </ul>	<p>DC</p> <p>24 V</p> <p>-3 to +5V</p> <p>+11 to +30V</p>
<b>Input current</b>	
<ul style="list-style-type: none"> <li>for signal "1", typ.</li> </ul>	2.5 mA
<b>Input delay (for rated value of input voltage)</b>	
<b>for standard inputs</b>	
<ul style="list-style-type: none"> <li>parameterizable</li> <li>at "0" to "1", min.</li> <li>at "0" to "1", max.</li> <li>at "1" to "0", min.</li> <li>at "1" to "0", max.</li> </ul>	<p>Yes; none / 0.05 / 0.1 / 0.4 / 1.6 / 3.2 / 12.8 / 20 ms</p> <p>4 µs; for parameterization "none"</p> <p>20 ms</p> <p>4 µs; for parameterization "none"</p> <p>20 ms</p>
<b>for interrupt inputs</b>	
<ul style="list-style-type: none"> <li>parameterizable</li> </ul>	Yes; Same as for standard inputs

for counter/technological functions	
— parameterizable	Yes; Same as for standard inputs
<b>Cable length</b>	
• shielded, max.	1 000 m; 600 m for technological functions; depending on input frequency, encoder and cable quality; max. 50 m at 100 kHz
• unshielded, max.	600 m; For technological functions: No
<b>Digital outputs</b>	
Type of digital output	Transistor
integrated channels (DO)	16
Current-sourcing	Yes; Push-pull output
Short-circuit protection	Yes; electronic/thermal
• Response threshold, typ.	1.6 A with standard output, 0.5 A with high-speed output; see manual for details
Limitation of inductive shutdown voltage to	-0.8 V
Controlling a digital input	Yes
Accuracy of pulse duration	Up to $\pm 100$ ppm $\pm 2$ $\mu$ s at high-speed output; see manual for details
minimum pulse duration	2 $\mu$ s; With High Speed output
<b>Digital output functions, parameterizable</b>	
• Switching tripped by comparison values	Yes; As output signal of a high-speed counter
• PWM output	Yes
— Number, max.	4
— Cycle duration, parameterizable	Yes
— ON period, min.	0 %
— ON period, max.	100 %
— Resolution of the duty cycle	0.0036 %; For S7 analog format, min. 40 ns
• Frequency output	Yes
• Pulse train	Yes; also for pulse/direction interface
<b>Switching capacity of the outputs</b>	
• with resistive load, max.	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed output; see manual for details
• on lamp load, max.	5 W; 1 W with high-speed output, i.e. when using a high-speed output; see manual for details
<b>Load resistance range</b>	
• lower limit	48 $\Omega$ ; 240 ohms with high-speed output, i.e. when using a high-speed output; see manual for details
• upper limit	12 k $\Omega$
<b>Output voltage</b>	
• Type of output voltage	DC
• for signal "0", max.	1 V; With high-speed output, i.e. when using a high-speed output; see manual for details
• for signal "1", min.	23.2 V; L+ (-0.8 V)
<b>Output current</b>	

<ul style="list-style-type: none"> <li>• for signal "1" rated value</li> </ul>	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed output, observe derating; see manual for details
<ul style="list-style-type: none"> <li>• for signal "1" permissible range, min.</li> </ul>	2 mA
<ul style="list-style-type: none"> <li>• for signal "1" permissible range, max.</li> </ul>	0.6 A; 0.12 A with high-speed output, i.e. when using a high-speed output, observe derating; see manual for details
<ul style="list-style-type: none"> <li>• for signal "0" residual current, max.</li> </ul>	0.5 mA
<b>Output delay with resistive load</b>	
<ul style="list-style-type: none"> <li>• "0" to "1", max.</li> </ul>	200 µs
<ul style="list-style-type: none"> <li>• "1" to "0", max.</li> </ul>	500 µs; Load-dependent
<b>for technological functions</b>	
— "0" to "1", max.	5 µs; Depending on the output used, see additional description in manual
— "1" to "0", max.	5 µs; Depending on the output used, see additional description in manual
<b>Parallel switching of two outputs</b>	
<ul style="list-style-type: none"> <li>• for logic links</li> </ul>	Yes; For technological functions: No
<ul style="list-style-type: none"> <li>• for uprating</li> </ul>	No
<ul style="list-style-type: none"> <li>• for redundant control of a load</li> </ul>	Yes; For technological functions: No
<b>Switching frequency</b>	
<ul style="list-style-type: none"> <li>• with resistive load, max.</li> </ul>	100 kHz; For high-speed output, 100 Hz for standard output
<ul style="list-style-type: none"> <li>• with inductive load, max.</li> </ul>	0.5 Hz; Acc. to IEC 60947-5-1, DC-13; observe derating curve
<ul style="list-style-type: none"> <li>• on lamp load, max.</li> </ul>	10 Hz
<b>Total current of the outputs</b>	
<ul style="list-style-type: none"> <li>• Current per channel, max.</li> </ul>	0.5 A; see additional description in the manual
<ul style="list-style-type: none"> <li>• Current per group, max.</li> </ul>	8 A; see additional description in the manual
<ul style="list-style-type: none"> <li>• Current per power supply, max.</li> </ul>	4 A; 2 power supplies for each group, current per power supply max. 4 A, see additional description in manual
<b>for technological functions</b>	
— Current per channel, max.	0.5 A; see additional description in the manual
<b>Cable length</b>	
<ul style="list-style-type: none"> <li>• shielded, max.</li> </ul>	1 000 m; 600 m for technological functions; depending on output frequency, load, and cable quality; max. 50 m at 100 kHz
<ul style="list-style-type: none"> <li>• unshielded, max.</li> </ul>	600 m; For technological functions: No
<b>Analog inputs</b>	
Number of analog inputs	5; 4x for U/I, 1x for R/RTD
<ul style="list-style-type: none"> <li>• For current measurement</li> </ul>	4; max.
<ul style="list-style-type: none"> <li>• For voltage measurement</li> </ul>	4; max.
<ul style="list-style-type: none"> <li>• For resistance/resistance thermometer measurement</li> </ul>	1
permissible input voltage for voltage input (destruction limit), max.	28.8 V
permissible input current for current input (destruction limit), max.	40 mA

Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
Technical unit for temperature measurement adjustable	Yes; °C/°F/K
<b>Input ranges (rated values), voltages</b>	
• 0 to +10 V	Yes; Physical measuring range: ± 10 V
• Input resistance (0 to 10 V)	100 kΩ
• 1 V to 5 V	Yes; Physical measuring range: ± 10 V
• Input resistance (1 V to 5 V)	100 kΩ
• -10 V to +10 V	Yes
• Input resistance (-10 V to +10 V)	100 kΩ
• -5 V to +5 V	Yes; Physical measuring range: ± 10 V
• Input resistance (-5 V to +5 V)	100 kΩ
<b>Input ranges (rated values), currents</b>	
• 0 to 20 mA	Yes; Physical measuring range: ± 20 mA
• Input resistance (0 to 20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
• -20 mA to +20 mA	Yes
• Input resistance (-20 mA to +20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
• 4 mA to 20 mA	Yes; Physical measuring range: ± 20 mA
• Input resistance (4 mA to 20 mA)	50 Ω; Plus approx. 55 ohm for overvoltage protection by PTC
<b>Input ranges (rated values), resistance thermometer</b>	
• Ni 100	Yes; Standard/climate
• Input resistance (Ni 100)	10 MΩ
• Pt 100	Yes; Standard/climate
• Input resistance (Pt 100)	10 MΩ
<b>Input ranges (rated values), resistors</b>	
• 0 to 150 ohms	Yes; Physical measuring range: 0 ... 600 ohms
• Input resistance (0 to 150 ohms)	10 MΩ
• 0 to 300 ohms	Yes; Physical measuring range: 0 ... 600 ohms
• Input resistance (0 to 300 ohms)	10 MΩ
• 0 to 600 ohms	Yes
• Input resistance (0 to 600 ohms)	10 MΩ
<b>Cable length</b>	
• shielded, max.	800 m; for U/I, 200 m for R/RTD
<b>Analog outputs</b>	
integrated channels (AO)	2
Voltage output, short-circuit protection	Yes
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
<b>Output ranges, voltage</b>	
• 0 to 10 V	Yes
• 1 V to 5 V	Yes



• -10 V to +10 V	Yes
<b>Output ranges, current</b>	
• 0 to 20 mA	Yes
• -20 mA to +20 mA	Yes
• 4 mA to 20 mA	Yes
<b>Load impedance (in rated range of output)</b>	
• with voltage outputs, min.	1 k $\Omega$
• with voltage outputs, capacitive load, max.	100 nF
• with current outputs, max.	500 $\Omega$
• with current outputs, inductive load, max.	1 mH
<b>Cable length</b>	
• shielded, max.	200 m

### Analog value generation for the inputs

<b>Integration and conversion time/resolution per channel</b>	
• Resolution with overrange (bit including sign), max.	16 bit
• Integration time, parameterizable	Yes; 2.5 / 16.67 / 20 / 100 ms, acts on all channels
• Interference voltage suppression for interference frequency f1 in Hz	400 / 60 / 50 / 10
<b>Smoothing of measured values</b>	
• parameterizable	Yes
• Step: None	Yes
• Step: low	Yes
• Step: Medium	Yes
• Step: High	Yes

### Analog value generation for the outputs

<b>Integration and conversion time/resolution per channel</b>	
• Resolution with overrange (bit including sign), max.	16 bit
<b>Settling time</b>	
• for resistive load	1.5 ms
• for capacitive load	2.5 ms
• for inductive load	2.5 ms

### Encoder

<b>Connection of signal encoders</b>	
• for voltage measurement	Yes
• for current measurement as 4-wire transducer	Yes
• for resistance measurement with two-wire connection	Yes
• for resistance measurement with three-wire connection	Yes

<ul style="list-style-type: none"> <li>• for resistance measurement with four-wire connection</li> </ul>	Yes
<b>Connectable encoders</b>	
<ul style="list-style-type: none"> <li>• 2-wire sensor</li> </ul>	Yes
<ul style="list-style-type: none"> <li>— permissible quiescent current (2-wire sensor), max.</li> </ul>	1.5 mA
<b>Encoder signals, incremental encoder (asymmetrical)</b>	
<ul style="list-style-type: none"> <li>• Input voltage</li> </ul>	24 V
<ul style="list-style-type: none"> <li>• Input frequency, max.</li> </ul>	100 kHz
<ul style="list-style-type: none"> <li>• Counting frequency, max.</li> </ul>	400 kHz; with quadruple evaluation
<ul style="list-style-type: none"> <li>• Signal filter, parameterizable</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Incremental encoder with A/B tracks, 90° phase offset</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Incremental encoder with A/B tracks, 90° phase offset and zero track</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Pulse encoder</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Pulse encoder with direction</li> </ul>	Yes
<ul style="list-style-type: none"> <li>• Pulse encoder with one impulse signal per count direction</li> </ul>	Yes
<b>Errors/accuracies</b>	
Linearity error (relative to input range), (+/-)	0.1 %
Temperature error (relative to input range), (+/-)	0.005 %/K
Crosstalk between the inputs, max.	-60 dB
Repeat accuracy in steady state at 25 °C (relative to input range), (+/-)	0.05 %
Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-)	0.02 %
Linearity error (relative to output range), (+/-)	0.15 %
Temperature error (relative to output range), (+/-)	0.005 %/K
Crosstalk between the outputs, max.	-80 dB
Repeat accuracy in steady state at 25 °C (relative to output range), (+/-)	0.05 %
<b>Operational error limit in overall temperature range</b>	
<ul style="list-style-type: none"> <li>• Voltage, relative to input range, (+/-)</li> </ul>	0.3 %
<ul style="list-style-type: none"> <li>• Current, relative to input range, (+/-)</li> </ul>	0.3 %
<ul style="list-style-type: none"> <li>• Resistance, relative to input range, (+/-)</li> </ul>	0.3 %
<ul style="list-style-type: none"> <li>• Resistance thermometer, relative to input range, (+/-)</li> </ul>	Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K
<ul style="list-style-type: none"> <li>• Voltage, relative to output range, (+/-)</li> </ul>	0.3 %
<ul style="list-style-type: none"> <li>• Current, relative to output range, (+/-)</li> </ul>	0.3 %
<b>Basic error limit (operational limit at 25 °C)</b>	
<ul style="list-style-type: none"> <li>• Voltage, relative to input range, (+/-)</li> </ul>	0.2 %
<ul style="list-style-type: none"> <li>• Current, relative to input range, (+/-)</li> </ul>	0.2 %

- Resistance, relative to input range, (+/-) 0.2 %
- Resistance thermometer, relative to input range, (+/-) Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K
- Voltage, relative to output range, (+/-) 0.2 %
- Current, relative to output range, (+/-) 0.2 %

**Interference voltage suppression for  $f = n \times (f_1 \pm 1 \%)$ ,  $f_1 =$  interference frequency**

- Series mode interference (peak value of interference < rated value of input range), min. 30 dB
- Common mode voltage, max. 10 V
- Common mode interference, min. 60 dB; at 400 Hz: 50 dB

**Interfaces**

Number of PROFINET interfaces 1

**1. Interface**

**Interface types**

- Number of ports 2
- integrated switch Yes
- RJ 45 (Ethernet) Yes; X1

**Functionality**

- PROFINET IO Controller Yes
- PROFINET IO Device Yes
- SIMATIC communication Yes
- Open IE communication Yes
- Web server Yes
- Media redundancy Yes

**PROFINET IO Controller**

**Services**

- PG/OP communication Yes
- S7 routing Yes
- Isochronous mode Yes
- Open IE communication Yes
- IRT Yes
- MRP Yes; As MRP redundancy manager and/or MRP client; max. number of devices in the ring: 50
- MRPD Yes; Requirement: IRT
- Prioritized startup Yes; Max. 32 PROFINET devices
- Number of connectable IO Devices, max. 128; In total, up to 256 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
- Of which IO devices with IRT, max. 64
- Number of connectable IO Devices for RT, max. 128
- of which in line, max. 128

- Number of IO Devices that can be simultaneously activated/deactivated, max.
- Number of IO Devices per tool, max.
- Updating times

8; in total across all interfaces

8

The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data

#### Update time for IRT

- for send cycle of 250  $\mu$ s
- for send cycle of 500  $\mu$ s
- for send cycle of 1 ms
- for send cycle of 2 ms
- for send cycle of 4 ms
- With IRT and parameterization of "odd" send cycles

250  $\mu$ s to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625  $\mu$ s of the isochronous OB is decisive

500  $\mu$ s to 8 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625  $\mu$ s of the isochronous OB is decisive

1 ms to 16 ms

2 ms to 32 ms

4 ms to 64 ms

Update time = set "odd" send clock (any multiple of 125  $\mu$ s: 375  $\mu$ s, 625  $\mu$ s ... 3 875  $\mu$ s)

#### Update time for RT

- for send cycle of 250  $\mu$ s
- for send cycle of 500  $\mu$ s
- for send cycle of 1 ms
- for send cycle of 2 ms
- for send cycle of 4 ms

250  $\mu$ s to 128 ms

500  $\mu$ s to 256 ms

1 ms to 512 ms

2 ms to 512 ms

4 ms to 512 ms

#### PROFINET IO Device

##### Services

- PG/OP communication
- S7 routing
- Isochronous mode
- Open IE communication
- IRT
- MRP
- MRPD
- PROFINergy
- Shared device
- Number of IO Controllers with shared device, max.

Yes

Yes

No

Yes

Yes

Yes

Yes; Requirement: IRT

Yes

Yes

4

#### Interface types

##### RJ 45 (Ethernet)

- 100 Mbps
- Autonegotiation
- Autocrossing
- Industrial Ethernet status LED

Yes

Yes

Yes

Yes

## Protocols

Number of connections	
• Number of connections, max.	96; via integrated interfaces of the CPU and connected CPs / CMs
• Number of connections reserved for ES/HMI/web	10
• Number of connections via integrated interfaces	64
• Number of S7 routing paths	16
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	Yes
— Open IE communication	Yes
— IRT	Yes
— MRP	Yes; As MRP redundancy manager and/or MRP client; max. number of devices in the ring: 50
— MRPD	Yes; Requirement: IRT
— PROFinergy	Yes
— Prioritized startup	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	128; In total, up to 256 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
— Of which IO devices with IRT, max.	64
— Number of connectable IO Devices for RT, max.	128
— of which in line, max.	128
— Number of IO Devices that can be simultaneously activated/deactivated, max.	8; in total across all interfaces
— Number of IO Devices per tool, max.	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
SIMATIC communication	
• S7 communication, as server	Yes
• S7 communication, as client	Yes
• User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
— several passive connections per port, supported	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte

<ul style="list-style-type: none"> <li>• UDP <ul style="list-style-type: none"> <li>— Data length, max.</li> </ul> </li> <li>• DHCP</li> <li>• SNMP</li> <li>• DCP</li> <li>• LLDP</li> </ul>	<p>Yes</p> <p>1 472 byte</p> <p>No</p> <p>Yes</p> <p>Yes</p> <p>Yes</p>
<b>Web server</b>	
<ul style="list-style-type: none"> <li>• HTTP</li> <li>• HTTPS</li> </ul>	<p>Yes; Standard and user pages</p> <p>Yes; Standard and user pages</p>
<b>OPC UA</b>	
<ul style="list-style-type: none"> <li>• OPC UA Server <ul style="list-style-type: none"> <li>— Application authentication</li> <li>— Security policies</li> <li>— User authentication</li> </ul> </li> </ul>	<p>Yes; Data access (read, write, subscribe), runtime license required</p> <p>Yes</p> <p>Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256</p> <p>"anonymous" or by user name &amp; password</p>
<b>Further protocols</b>	
<ul style="list-style-type: none"> <li>• MODBUS</li> </ul>	<p>Yes; MODBUS TCP</p>
<b>Media redundancy</b>	
<ul style="list-style-type: none"> <li>• Switchover time on line break, typ.</li> <li>• Number of stations in the ring, max.</li> </ul>	<p>200 ms; For MRP, bumpless for MRPD</p> <p>50</p>
<b>Isochronous mode</b>	
<p>Isochronous operation (application synchronized up to terminal)</p>	<p>Yes; With minimum OB 6x cycle of 625 µs</p>
<p>Equidistance</p>	<p>Yes</p>
<b>S7 message functions</b>	
<p>Number of login stations for message functions, max.</p>	<p>32</p>
<p>Block related messages</p>	<p>Yes</p>
<p>Number of configurable alarms, max.</p>	<p>5 000</p>
<p>Number of simultaneously active alarms in alarm pool</p> <ul style="list-style-type: none"> <li>• Number of reserved user alarms</li> <li>• Number of reserved alarms for system diagnostics</li> <li>• Number of reserved alarms for Motion Control technology objects</li> </ul>	<p>300</p> <p>100</p> <p>80</p>
<b>Test commissioning functions</b>	
<p>Joint commission (Team Engineering)</p>	<p>Yes; Parallel online access possible for up to 5 engineering systems</p>
<p>Status block</p>	<p>Yes; Up to 8 simultaneously (in total across all ES clients)</p>
<p>Single step</p>	<p>No</p>
<b>Status/control</b>	

<ul style="list-style-type: none"> <li>• Status/control variable</li> <li>• Variables</li> <li>• Number of variables, max. <ul style="list-style-type: none"> <li>— of which status variables, max.</li> <li>— of which control variables, max.</li> </ul> </li> </ul>	<p>Yes</p> <p>Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters</p> <p>200; per job</p> <p>200; per job</p>
<b>Forcing</b>	
<ul style="list-style-type: none"> <li>• Forcing, variables</li> <li>• Number of variables, max.</li> </ul>	<p>Peripheral inputs/outputs</p> <p>200</p>
<b>Diagnostic buffer</b>	
<ul style="list-style-type: none"> <li>• present</li> <li>• Number of entries, max. <ul style="list-style-type: none"> <li>— of which powerfail-proof</li> </ul> </li> </ul>	<p>Yes</p> <p>1 000</p> <p>500</p>
<b>Traces</b>	
<ul style="list-style-type: none"> <li>• Number of configurable Traces</li> </ul>	<p>4; Up to 512 KB of data per trace are possible</p>
<b>Interrupts/diagnostics/status information</b>	
<b>Alarms</b>	
<ul style="list-style-type: none"> <li>• Diagnostic alarm</li> <li>• Hardware interrupt</li> </ul>	<p>Yes</p> <p>Yes</p>
<b>Diagnostic messages</b>	
<ul style="list-style-type: none"> <li>• Monitoring the supply voltage</li> <li>• Wire-break</li> <li>• Short-circuit</li> <li>• A/B transition error at incremental encoder</li> </ul>	<p>Yes</p> <p>Yes; for analog inputs/outputs, see description in manual</p> <p>Yes; for analog outputs, see description in manual</p> <p>Yes</p>
<b>Diagnostics indication LED</b>	
<ul style="list-style-type: none"> <li>• RUN/STOP LED</li> <li>• ERROR LED</li> <li>• MAINT LED</li> <li>• Monitoring of the supply voltage (PWR-LED)</li> <li>• Channel status display</li> <li>• for channel diagnostics</li> <li>• Connection display LINK TX/RX</li> </ul>	<p>Yes</p> <p>Yes</p> <p>Yes</p> <p>Yes</p> <p>Yes</p> <p>Yes; For analog inputs/outputs</p> <p>Yes</p>
<b>Supported technology objects</b>	
<p>Motion Control</p> <ul style="list-style-type: none"> <li>• Number of available Motion Control resources for technology objects (except cam disks)</li> <li>• Required Motion Control resources <ul style="list-style-type: none"> <li>— per speed-controlled axis</li> <li>— per positioning axis</li> <li>— per synchronous axis</li> </ul> </li> </ul>	<p>Yes; Note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER</p> <p>800</p> <p>40</p> <p>80</p> <p>160</p>

— per external encoder	80
— per output cam	20
— per cam track	160
— per probe	40
• Positioning axis	
— Number of positioning axes at motion control cycle of 4 ms (typical value)	5
— Number of positioning axes at motion control cycle of 8 ms (typical value)	10
<b>Controller</b>	
• PID_Compact	Yes; Universal PID controller with integrated optimization
• PID_3Step	Yes; PID controller with integrated optimization for valves
• PID-Temp	Yes; PID controller with integrated optimization for temperature
<b>Counting and measuring</b>	
• High-speed counter	Yes
<b>Integrated Functions</b>	
Number of counters	6; Of which max. 4x A/B/N
Counting frequency (counter) max.	400 kHz; with quadruple evaluation
<b>Counting functions</b>	
• Continuous counting	Yes
• Counter response parameterizable	Yes
• Hardware gate via digital input	Yes
• Software gate	Yes
• Event-controlled stop	Yes
• Synchronization via digital input	Yes
• Counting range, parameterizable	Yes
<b>Comparator</b>	
— Number of comparators	2; per count channel; see manual for details
— Direction dependency	Yes
— Can be changed from user program	Yes
<b>Position detection</b>	
• Incremental acquisition	Yes
• Suitable for S7-1500 Motion Control	Yes
<b>Measuring functions</b>	
• Measuring time, parameterizable	Yes
• Dynamic measurement period adjustment	Yes
• Number of thresholds, parameterizable	2
<b>Measuring range</b>	
— Frequency measurement, min.	0.04 Hz
— Frequency measurement, max.	400 kHz; with quadruple evaluation
— Cycle duration measurement, min.	2.5 μs



— Cycle duration measurement, max.	25 s
<b>Accuracy</b>	
— Frequency measurement	100 ppm; depending on measuring interval and signal evaluation
— Cycle duration measurement	100 ppm; depending on measuring interval and signal evaluation
— Velocity measurement	100 ppm; depending on measuring interval and signal evaluation
<b>Potential separation</b>	
<b>Potential separation digital inputs</b>	
• between the channels	No
• between the channels, in groups of	16
<b>Potential separation digital outputs</b>	
• between the channels	No
• between the channels, in groups of	16
<b>Potential separation channels</b>	
• between the channels and backplane bus	Yes
• Between the channels and load voltage L+	No
<b>Isolation</b>	
Isolation tested with	707 V DC (type test)
<b>Ambient conditions</b>	
<b>Ambient temperature during operation</b>	
• horizontal installation, min.	0 °C
• horizontal installation, max.	60 °C; Note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
• vertical installation, min.	0 °C
• vertical installation, max.	40 °C; Note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off
<b>Configuration</b>	
<b>Programming</b>	
<b>Programming language</b>	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
<b>Know-how protection</b>	
• User program protection	Yes
• Copy protection	Yes
• Block protection	Yes
<b>Access protection</b>	
• Password for display	Yes

- Protection level: Write protection Yes
- Protection level: Read/write protection Yes
- Protection level: Complete protection Yes

#### Cycle time monitoring

- lower limit adjustable minimum cycle time
- upper limit adjustable maximum cycle time

#### Dimensions

Width	85 mm
Height	147 mm
Depth	129 mm

#### Weights

Weight, approx.	1 050 g
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**last modified:** 12/06/2016